Application Note



AS2100 Laser Distance Sensor

Getting started with EtherNet/IP™

V1.00

Abstract

This Application Note describes a simple example of use to get started with the EtherNet/IP™ interface of the Acuity AS2100 laser distance sensors.

This Application Note is provided as is without any warranty for any problems this sample may cause.

Table of Contents

1 Document scope	3
2 Safety instructions	3
3 Introduction	4
3.1 Overview	4
3.2 Prerequisites – Hardware & Software	4
4 Description file (EDS)	5
5 Module configuration	5
5.1 New / Add module	5
5.2 Connection configuration	
5.3 RPI configuration	
6 Connection established	
7 Parameter	9
8 Controller tags – Input / Output	10
9 Controller tags – All	10
10 PLC application	11
10.1 Main routine	11
10.2 Local tags	
10.3 Measurement control	
10.4 Acyclic read / write services.	
10.5 Reset acyclic values	
11 IP parameter	
11.1 Logix Designer	
11.2 RSLinx	
12 Glossary	
13 Revision history	19

1 Document scope

This document covers an Application Note written for the Acuity AS2100 Laser Distance Sensors with EtherNet/IP™ interface. The following topics are discussed:

- Safety instructions
- Application Note descriptions

2 Safety instructions



This Application Note is written for qualified system integrators to help doing an application specific sensor configuration.



Looking into the laser beam may be hazardous to the eyes.

• Do not look into the laser beam. Make sure the laser is aimed above or below eye level. (particularly with fixed installations, in machines, etc.).



Take precaution against electrostatic discharge (ESD) when the AS2100 laser distance sensors exchangeable cover is open.

- Generally the sensor with removed exchangeable cover is a sensitive device and can be damaged by electrostatic discharge.
- Only handle the device properly grounded and with care.
- No warranty will be granted on improper handling and / or ESD caused problems.

3 Introduction

3.1 Overview

This document contains a simple application of use to start with the EtherNet/IP™ interfaces of the Acuity AS2100 laser distance sensor. The simple example includes the relevant information and instructions to get started with the corresponding PLC and to handle the process data and the acyclic read / write services of the sensor.

This document describes a simple example of use to get started with the EtherNet/IP™ interface of the Acuity AS2100 laser distance sensor. All information and instructions necessary to understand this example of use and to run it on an Allen Bradley CompactLogix PLC are included.

The following functions are covered by this example:

- Process input / output data
 - Measurement Control Start / Stop continuous distance measurement
 - Distance Integer / Distance Float Distance data of the laser sensor
 - Distance Unit Selected distance unit number for distance data
- Acyclic read / write services
 - Serial Number Read serial number of laser sensor
 - Distance Unit Read / Write distance unit number for distance data

Additionally, the following protocol specific features are covered too:

Configuration / Change of IP address

For detail information about the laser sensor or the EtherNet/IP™ interface, please see the AS2100 Manual on the Acuity website (www.acuitylaser.com).

For questions, comments or technical support concerning this document please contact Acuity technical support. Please note, we are able to support you regarding our laser distance sensor but we only have limited support possibilities regarding the EtherNet/IP™ networks as well as for the used PLC's.

3.2 Prerequisites – Hardware & Software

The following hardware and software are used to create this example:

- PLC hardware: Allen Bradley CompactLogix 1769-L30ER
- PLC software: Studio 5000 Logix Designer V24 Ensure the Logix Designer software is installed and running correctly.
- Sensor hardware: AS2100 laser distance sensor with correct assembled EtherNet/IP™ interface
- Sensor software: Only the EDS file of the AS2100 sensor. No additional sensor software.

Remark: The Logix Designer V24 is not the newest version, but for this simple example sufficient for the used basic functions. As additional information: Starting with the version V32, unsigned data types are now also supported.

Most Allen Bradly PLC's have a "RUN/REM/PROG" switch. For example, this switch must be set to PROG to load / program the PLC project onto the PLC.

The "RUN/REM/PROG" switch must be set to RUN to set the RUN flag in the Run/Idle header of the process data frames. Otherwise the output data will not be taken over in the AS2100 laser distance sensor and the safe values of the device are activated.

The "RUN/REM/PROG" switch must be set to RUN to set the RUN flag in the Run/Idle header of the process data frames. Otherwise the AS2100 laser distance sensor does not take over the output data and the safe values of the device are activated.



4 Description file (EDS)

First of all the EDS file of the laser distance sensor must be added / installed. This can be done over the Logix Designer software menu, Tools \rightarrow EDS Hardware Installation Tool. Then select the right EDS file path for the installation. See figure 1 and 2 for more details.

The latest EDS file for the Acuity AS2100 distance sensor with EtherNet/IP™ can be downloaded from www.acuitylaser.com.

Too	ls <u>W</u> indow <u>H</u> elp	
	Options	
	Security	•
ø	Documentation <u>L</u> anguages	
	Import	•
	<u>E</u> xport	
9	EDS Hardware Installation Tool	
	<u>M</u> otion	•
	Custom Tools	
đ	ControlFLASH	

Figure 1: Studio 5000 software menu, Tools \rightarrow EDS Hardware Installation Tool.

Automation applications. Register a gingle file Register a directory of EDS files Look in s Lamed: ACUITY_LaserDistanceSensorAS2100_EIP,	use in Rockwell	Y
Register a directory of EDS files Look in s AcUITY_LaserDistanceSensorAS2100_EIP If there is an icon file (ico) with the same name as the then this image will be associated with the device.		
ACUITY_LaserDistanceSensorAS2100_EIP,		
ACUITY_LaserDistanceSensorAS2100_EIP if there is an icon file (ico) with the same name as the then this image will be associated with the device.	ofolders	
ACUITY_LaserDistanceSensorAS2100_EIP if there is an icon file (ico) with the same name as the then this image will be associated with the device.		
• If there is an icon file (ico) with the same name as the then this image will be associated with the device.	/1_1.eds Browse	1
then this image will be associated with the device.		-
then this image will be associated with the device.		
then this image will be associated with the device.		
then this image will be associated with the device.		
then this image will be associated with the device.	file(s) you are registering	
To perform an install	inologious and registering	
	inclos you are registering	
		Nex
	ion test on the file(s), click	Nex

Figure 2: Rockwell Automation's EDS Wizard. Selection and installation of the EDS source file.

After this step the AS2100 Laser Distance Sensor will be available in the module catalog of the Logix Designer software as a EtherNet/IP™ module. For details see the next chapter 5.

5 Module configuration

5.1 New / Add module

The Laser Distance Sensor adapter device can now be added using the context menu entry New Module. Then the corresponding device can be selected and added to the network. For details see figure 3 and 4.



5 Module configuration

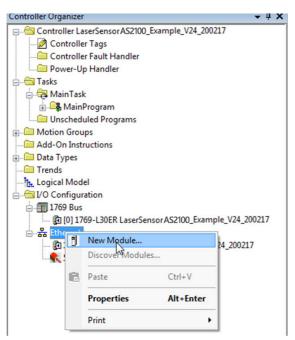


Figure 3: Controller Organizer – Context menu (right click) \rightarrow New Module... to add a new module to the network

alog Modulerkennung Favoriten			
dx400	Filter Löschen		Filter anzeigen 🛛 💝
Catalog Number	Description	Vendor	Category
50063x and 500702	Laser Distance Sensor AS2100	ACUITY	Generic Device(keyable)
.4		11	,

Figure 4: Module type selection – Select the corresponding module type, in this example "Laser Distance Sensor AS2100". Optional use the filter possibility to filter the available module types.

5.2 Connection configuration

The configuration of the connection type to "I/O Basic" is done in figure 5. This configuration allows the input and output (I/O) data exchange and handling.

Connection types	Descriptions
I/O Basic	Allows the handling of input and output (I/O) data of the module.
Listen Only Basic	Allows a second connection (listen only) to an already existing connection.
Input Only Basic	Allows only the handling of the input data of the module.

Remark: Important differences between the connection types in the table below.



5 Module configuration

Controller Organizer 👻 🕂 🗙					
Controller LaserSensorAS2100_Example_V24_200217	Module Pro	operties: Local (50065x and 500702 1.001)			<u>9</u>
	General Co	onnection Module Info Parameters Internet Protocol Port	Configuration Network		
	Vendor:				
😸 🕞 MainProgram	Parent:	Local			
Unscheduled Programs	Name:	A52100	Ethernet Address		
	Description		Private Network:	192.168.1. 10	
	Descrigion		A		
			IP Address:		
			C Host Name:		
Controller LaserSensorAS2100_Example_V24_200217 Controller Tags Controller Tags Controller Tags Controller Kub Handler Power: Up Handler					
🖨 🎹 1769 Bus					
	Module D	Definition			
	Revision	: 1.001			
	Bectronic	c Keying: Compatible Module			
	Connecti	ions: VO Basic, Assembly Instance Input Basic=150			
		Change			
Controller Lased-ensorAS2100_Example_V24_20027 Controller Tays Controller Tays Controller Tays Controller Faust Handler Controller Controller Faust Handler Controller Faust Handler Controller Controler Control					
	Modu	ule Definition			
	Revision	n: 1 • 001 💠			
	Electron	ic Reying: Compatible Module			
	Connect	tions:			
	Nam	9		Remote Data	
	VO E	Basic	Input:	Assembly Instance Input Basic	150
			Output:	Assembly Instance Output Basic	100
	001		N		
	Liste	en Only Basic	48		
	inpo				
				OK	Cancel Help
Controller Opportunity R. Lonier Company		NAME OF TAXABLE PARTY.			

Figure 5: Module properties (General tab) – Change the connection type to "I/O Basic" (Exclusive-Owner connection). Module Properties \rightarrow General tab \rightarrow Change... button \rightarrow Selection of "I/O Basic".

5.3 RPI configuration

The configuration of the process data interval time for the selected Laser Distance Sensor is available in the module properties configuration windows (see figure 6 for details). The interval time can be chosen between 1 ms and 100 ms (maximum).

Remark: The RPI value for older PLC systems is limited to a minimum of 2 ms.

5 Module configuration

Name	Requested Packet Interval (RPI) (ms)	Connection over EtherNet/IP	Input Trigger	
VO Basic, Assembly Instance Input Basic = 15	0, 1.0 ≑ 1.0 - 100.0	Unicast 👤	Cyclic	-
	\$			
Inhibit Module	: While in Run Mode			
Module Fault				

Figure 6: Module properties (Connection tab) – Change the Requested Packet Interval (RPI) of the cyclic process data. In this example: 1 ms.

6 Connection established

The establishment of a connection can be achieved by selecting the online mode. This can be done according the details in figure 7.

Offline	RUN L
No Forces	<u>G</u> o Online
No Edits	Upload
	<u>D</u> ownload
	Program Mode
Controller Organize	<u>R</u> un Mode
🖃	<u>T</u> est Mode
🖉 Controll	Clear Faults
Controll	-
Power-L	G <u>o</u> To Faults
🖶 🖂 Tasks	Controller Properties
📄 🛱 MainTa	

Figure 7: Connection establishment – Go Online to establish connection.

Once the connection is established, the status in the module properties window status bar at the bottom is switched to "Running". The status in the status bar is marked in figure 8.



General Co	nnection	Module Info	Parameters	Internet Protocol	Port Conf	iguration	Network	
Type: Vendor: Parent: Na <u>m</u> e: Descri <u>p</u> tion	ACU Loca	IITY	2 Laser Distar	ce Sensor AS2100		Ethemet @ Priva O IP Ac D Host	te Network: Idress:	192.168.1. 10 ÷
Module I Revision Electroni Connect	: c Keying:			ince Input Basic=1 Change				

Figure 8: Module properties - Connection status: "Running" (for established connection)

7 Parameter

The parameter table in figure 9 is continuously updated with sensor data as soon as the connection is established (Online mode). This will be done automatically with the acyclic EtherNet/IPTM read services (Get_Attribute_Single). The parameter group selection offers the possibility to select all parameter or a desired parameter group only.

Remark: The selection of parameter groups is an unlocked feature of the AOP (AOP key in the EDS file). These parameter groups corresponds also to the AS2100 EtherNet/IPTM Manual.

<u> </u>								
L. M	odule Pro	operties: Local (50063x and 500702	1.001)					
			· · · · · · · · · · · · · · · · · · ·					A
Ge	neral Co	nnection Module Info Parameters	Internet Protocol Port Configuration Network					
								=
G		<all parameters=""></all>						
П		<all parameters=""></all>	Value	11.03.0	Ot de	٦.		
				Units	Style	6		
	8193	Measurement	Start measurem			-		
	0194	Measurement Configuration	- 0		Decimal 💂	4		
	8195	Options Input	Norr			- =		
	8196	Options Output Sensor State		l	Desired	- 11		
			8755	<u> </u>	Decimal .	4		
	8226	Optional Output Data 1 Optional Output Data 2	16909060		Decimal _	4		
	8228	Optional Output Data 2 Optional Output Data 3			Decimal Decimal	4		
		Distance Integer			Decimal .	4		
		Distance Float	0.0		Float	4		
	_	Signal Strength			Decimal	4		
		2 Temperature	• 0 • 0		Decimal	4		
		Measurement Actuality	No new measurem		Decinal	<u> </u>		
		Measurement Reserved			Decimal	Т		
	_	Sensor State	Er	<u> </u>	-	<u>ب</u> ۲		
	12021							
					,			
		to Defente			C-1 4			
	insert <u>r</u> ac	ctory Defaults			<u>S</u> et •			
- 1								
6	D They	values displayed here are read directly	from the module. These values are not stored in the controlle	and an	a not sent to the			
	modu	le when a connection is established.	Click Set to write updated values to the module.		S THOL BOTH TO THO			
Statu	us: Runni	ng	OK Cancel	Apply	/ <u>H</u> e	elp		-
1						_	-	· ·

Figure 9: Module properties (Parameter tab) – Parameter view (from EDS file) with available parameter group selections.

8 Controller tags – Input / Output

The controller tags are generated automatically by adding the module (AS2100 device) to the network. At the same time, also the mapping of the device process data into the AS2100:I (Input) and AS2100:O Output) tags will be done. The available input tags are shown in figure 11 and the available output tags in figure 12.

Remark: The Add-On-Profile (AOP) key to unlock additional features is integrated in the EDS file of the Acuity laser sensor (see figure 10 for this information). No action needs to be taken.

Entry Key	word	
I_IOC_D	etails_License	Commen
Field Valu	e (NOTE: In the EDS, this will appear as wri	tten herel)
	ie (NOTE: III die EDO, die will oppedi de will	
	e (NOTE, in the EBC, this will appear as will	Add
Field	Field Value	

Figure 10: Add-On-Profile (AOP) Key / License in EDS file – Unlocks additional features e.g. showing real data types instead of an unspecific data array

- 2 Controller Tags	Scope: @LaserSensorAS21 Show: Al Tags				• Y. Enter M			
Controller Fault Handler	Name	Alas For	Base Tag	Data Type	Description	External Access	Constant	Style
- Power-Up Handler	- AS21001			_058F-50063kand500702_0A1AE		Read/Write		
Tasks	AS2100:I ConnectionFaulted			BOOL	-	Read/Write		Decimal
😑 💱 MainTask	+ AS2100:I Distance_Integer			DINT		Read/Write	-	Decimal
🛞 🚔 MainProgram	AS2100:I Distance_Roat			REAL		Read/Write		Float
Unscheduled Programs Motion Groups	+ AS21001 Signal_Strength			DINT		Read/Write		Decimal
Add-On Instructions	+ AS21001 Temperature			INT		Read/Write		Decimal
Data Types	+ AS21001 Distance_Unit			SINT		Read/Write		Decimal
Trends	+ AS2100:I Measurement_Actuality			SINT		Read/Write		Decimal
Logical Model	+ AS2100:I Measurement_Reserved			INT		Read/Write		Decimal
1/O Configuration	+ AS2100:I Sensor_State			SINT		Read/Write	1	Decimal
1769 Bus	+ AS2100:I Sensor_Output_Data_Limit_Exceeded			SINT		Read/Write		Binary
0 [0] 1769-L30ER LaserSensor AS2100_Example_V24_200217	AS2100:I Measurement_Control			BOOL		Read/Write		Decimal
Ethernet	AS2100:I Optional_Output_Data_0			BOOL		Read/Write		Decimal
_ 1769-L30ER LaserSensor AS2100_Example_V24_200217	AS2100:1 Optional_Output_Data_1			BOOL		Read/Write		Decimal
\$0063x and \$00702 AS2100	AS2100:I Optional_Output_Data_2			BOOL		Read/Write	1	Decimal
	AS2100:I Optional_Output_Data_3			BOOL		Read/Write		Decimal
	AS2100:I Not_used1	12		BOOL		Read/Write		Decimal
	AS2100:I Not_used2			BOOL		Read/Write		Decimal
	AS21001 Not_used3			BOOL		Read/Write	3	Decimal
	+ AS21001 Sensor_Error_Code			INT		Read/Write		Decimal
	+ AS2100:I Optional_Input_Data_0			INT		Read/Write		Decimal
	+ AS2100:I Optional_Input_Data_1			DINT		Read/Write		Decimal
	+ AS2100:I Optional_Input_Data_2			DINT		Read/Write		Decimal
	+ AS21001 Optional_Input_Data_3			DINT		Read/Write		Decimal

Figure 11: Controller tags – Available input tags according EDS file (Name, data type, etc.)

ope: DLaserSensorAS21- Show: All Tags					▼ Y. Enter N.	ame Filter		
Name	_=== A	Alias For	Base Tag	Data Type	Description	External Access	Constant	Style
+-Distance_Unit_Read				SINT		Read/Write	1	Decimal
Distance_Unit_Read_Orl				BOOL		Read/Write		Decimal
				SINT		Read/Write		Decimal
Distance_Unit_Write_Ctrl				BOOL		Read/Write	1	Decimal
+ AS2100:I				_058F:50063xand500702_0A1AE		Read/Write		
- AS2100:0]		_058F:50063xand500702_BF8982		Read/Write		
+ AS2100;O.Measurement_Control				INT		Read/Write		Decimal
+ AS2100:O.Optional_Output_Data_0				INT		Read/Write		Decimal
+ AS2100:O.Optional_Output_Data_1				DINT		Read/Write	1	Decimal
+ AS2100:O Optional_Output_Data_2				DINT		Read/Write		Decimal
+ AS2100:O Optional_Output_Data_3				DINT		Read/Write		Decimal

Figure 12: Controller tags – Available output tags according EDS file (Name, data type, etc.)

9 Controller tags – All

The controller tag list in figure 13 shows all available controller tags. This list contains the already mentioned automatically generated tags during the module adding process (see the previous chapter 8) and some other tags used for this example.

Since the used PLC system has no digital I/O, tags were used to trigger the corresponding services (see the tags Serial_Number_Read_Ctrl, Distance_Unit_Read_Ctrl and Distance_Unit_Write_Ctrl).



Controller Organizer 👻 🕂 🗙	MainProgram - MainRoutine	
Controller LaserSensor AS2100_Example_V24_200217 Controller Tage Controller Fault Handler	● Manifoldane - Manifoldane 市場階目目 ● Manifoldane	
Controller Fault Handler Controller Fault Han	0 Measurement_StartStop	Move Control Control 14
Unacheduled Programs Motion Forous Add-On Instructions Data Types Trends - Trends - To Logical Model - Su Cogical Model	1 Measurement_StartStop	Move 1 Source 1 Dest AS21000 Measurement_Control 1
	S C Stor	OSR. Shot Raing ge Bt storage_bit.ReadSeriaNumber (SB) ut Bit output_bit_ReadSeriaNumber (OB)
		MSG Control ExplicitReadSerialNumber (CN)
	Stor	-OGR
	5 dutput_bit_ReadDistanceUnit Messag	e Control ExplicitReadDistanceUnt (CON)-++

Figure 13: Controller tags – All available tags in the controller. In gray \rightarrow Automatically generated tags (AS2100:I, AS2100:O). In white \rightarrow Manually created tags (e.g. Distance_Unit_Read).

10 PLC application

10.1 Main routine

In the task tree the "MainRoutine" program can be found (see figure 14 for details). This main routine consists of different program segments (called "rugs") used for this EtherNet/IPTM example.

Remark: All these "rugs" are processed continuously with the maximum possible PLC processing time.

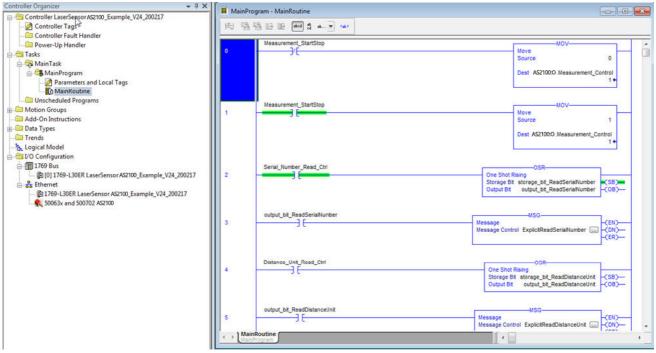


Figure 14: Main Program – Main Routine: View of the main program routines. PLC runs all program routines with max. possible cycle time.



10.2 Local tags

Local tags are temporary variable. In this example the local tags in figure 15 are used for triggering the acyclic services via OSR¹ blocks (for details see chapter 10.4.

ope: 🅞 Main Program 👻 Show: All Tags					•	Y. Enter Name Filter				
Name		Usage	Alias For	Base Tag	Data Type	Description	External Access	Constant	Style 4	Properties
output_bit_ReadDistanceUnit		Local			BOOL		Read/Write		Decin	🔃 👌 💷 🖌 Extended P
output_bit_ReadSerialNumber		Local			BOOL		Read/Write		Decin	General
output_bit_WriteDistanceUnit		Local			BOOL		Read/Write		Decin	⊟ Data
storage_bit_ReadDistanceUnit		Local			BOOL		Read/Write		Decin	Value
storage_bit_ReadSerialNumber		Local			BOOL		Read/Write		Decin	Force Mask
storage_bit_WriteDistanceUnit		Local			BOOL		Read/Write		Decin	Produced Connection
										Consumed Connection Parameter Connections {0:
									E	E
									E	

Figure 15: Main Program – List of local tags used in this example main program routines.

10.3 Measurement control

The "Measurement_Control", a part of the cyclic process output data, is used to start and stop the distance measurements of the laser distance sensor. In this example the "Measurement_Control" can be set to "1" or "0" with the associated controller tag. See figure 16 for the corresponding main routine 0 and 1.

	gram - MainRoutine 🍇 📴 📴 🕷 👶 🐨 👞	
0	Measurement, StartStop	Move 0 Source 0 Dest AS2100.0.Measurement_Control 1 +
1	Measurement_StartStop	Move Source 1 Dest AS2100:O.Measurement_Control

Figure 16: Main Program – Main Routine 0 & 1: Control of the process data output "Measurement Control" to start (1) / stop (0) distance measurements.

10.4 Acyclic read / write services

The acyclic read and write services are used to e.g. read device information and to configure the sensor. In this example the serial number and the distance unit are used to demonstrate the basic principle of reading or writing acyclic parameters. See chapter 10.4.3 to 10.4.5 for the corresponding routines.

10.4.1 Basic information (MSG messages)

The mentioned services can be programmed using the MSG instruction block. This block is available by default and no additions need to be added. Some selected information for the configuration of this block is shown in the table below. Detailed information can be found in the Rockwell documentation.

OSR (One Shot Rising) instruction: Detailed information for the OSR instruction can be found in the Rockwell documentation.

Message configuration	Descriptions
Message Type	CIP Generic as default.
Service Type	Service type e.g. "Get Attribute Single" for acyclic read service or "Set Attribute Single" for acyclic write service.
Class, Instance, Attribute	EtherNet/IP [™] access information of the corresponding parameter. See the AS2100 EtherNet/IP [™] for this information.
Error Code, Extended Error Code	In case of an error (.ER tag of the corresponding parameter is set, see figure 20 for details) the Error Code and Extended Error Code must be evaluated.
Timed Out	Not relevant.

In the figures 17, 18 and 19 the configurations used for the MSG instruction are shown (example to read out the serial number of the module).

Message Configuration - ExplicitReadSerialNumbe Configuration Communication Tag Message Type: CIP Generic	r bs	X
Service Type: Service Code: Instance: 1 Attribute: 1 (Hex) (Hex)	Source Element: Source Length: Destination Element:	v (Bytes) Serial_Number v New Tag
C Enable Enable Enable Waiting Start Error Code: Error Path: Error Text: OK		one Length: 4] Timed Out ← Deemehmen Hilfe

Figure 17: Message configuration (MSG) – Configuration tab: Configurations used to read the "Serial Number" (in this example).

Configuration Communic	ation Tag					Browse]
AS2100	Ŧ						
Communication Metho	d						
CIP DH+	Channel:	'A'	- D	estinatio	n Link:	0	A. V
CIP With Source ID	Source Link:	0	× D	estinatio	n Node:	0	(Octal)
Connected		Cach	e Connect	ions	F.	Large C	Connection
) Enable 🔾 Enable	Waiting) Start	0	Done	Done	Length: 4	ų.
) Error Code: Fror Path:	Extended	Error Code	e.		🔲 Ti	med Out 🗲	

Figure 18: Message configuration (MSG) – Communication tab: Configurations used to read the "Serial Number" (in this example).



10 PLC application

Configuration	Communication Ta	ag			
Name:	Explicit Read Serial	Number			
Description:			*		
			-		
Type:	Base				
Data Type:	MESSAGE				
Scope: External Access:	🔁 LaserSensorAS Read/Write	2100_Example_V	/24_200217		
) Enable) Enable Waiting	O Start	O Done	Done Length: 4	
Error Code:	Extend	ed Error Code:		🔲 Timed Out 🗲	
ror Path					

Figure 19: Message configuration (MSG) - Tag tab: No configuration used (in this example)

In of case of an error the Error Code and Extended Error Code in the .ER tag of the corresponding parameter must be evaluated. See figure 20 for more details.

-ExplicitReadSerialNumber	MESSAGE	Read/Write	
+ Explicit Read Serial Number. Flags	INT	Read/Write	Hex
-Explicit Read Serial Number. EW	BOOL	Read/Write	Decimal
-ExplicitReadSerialNumber.ER	BOOL	Read/Write	Decimal
-ExplicitReadSerialNumber.DN	BOOL	Read/Write	Decimal
-Explicit Read Serial Number. ST	BOOL	Read/Write	Decimal
-Explicit Read Serial Number. EN	BOOL	Read/Write	Decimal
-Explicit Read Serial Number. TO	BOOL	Read/Write	Decimal
-Explicit Read Serial Number. EN_CC	BOOL	Read/Write	Decimal
+ Explicit Read Serial Number. ERR	INT	Read/Write	Hex
+ ExplicitReadSerialNumber.EXERR	DINT	Read/Write	Hex
+ ExplicitReadSerialNumber.ERR_SRC	SINT	Read/Write	Decimal
Explicit Read Serial Number. Dive LEN	INT	Read/Write	Decimal
ExplicitReadSerialNumber.REQ_LEN	INT	Read/Write	Decimal
+ Explicit Read Serial Number Destination Link	INT	Read/Write	Decimal

Figure 20: Message configuration (MSG) - .ER tag of SerialNumber: This tag will be set in an error condition / error case.

10.4.2 Parameter initialization

For EtherNet/IP™ no specific parameter initialization procedure is used during the establishment of the connection. Consequential all device parameters can be simple configured after the connection is established by using the acyclic read and write services (MSG blocks) at the system start or if needed at anytime during operation.

10.4.3 Serial number – Read

The routines in figure 21 show the acyclic read service (MSG) to read the serial number of the module. This read service can be triggered with the associated controller tag "Serial_Number_Read_Ctrl". So that this acyclic message instruction is only done once, the OSR (One Shot Rising) instruction block is used in addition.



Figure 21: Main Program - Main Routine 2 & 3: Acyclic service (MSG) to read "Serial Number" of the device.



10.4.4 Distance unit – Read

The routines in figure 22 show the acyclic read service (MSG) to read the distance unit of the module. This read service can be triggered with the associated controller tag "Distance_Unit_Read_Ctrl". So that this acyclic message instruction is only done once, the OSR (One Shot Rising) instruction block is used in addition.

4	Distance_Unit_Read_Ctri	OSR- One Shot Rising Storage Bit storage_bit_ReadDistanceUnit Output Bit output_bit_ReadDistanceUnit (OB)-	
5	output_bit_ReadDistanceUnit	MSG	

Figure 22: Main Program – Main Routine 4 & 5: Acyclic service (MSG) to read "Distance Unit" of the device.

10.4.5 Distance unit – Write

The routines in figure 23 show the acyclic write service (MSG) to write the distance unit of the module. This write service can be triggered with the associated controller tag "Distance_Unit_Write_Ctrl". So that this acyclic message instruction is only done once, the OSR (One Shot Rising) instruction block is used in addition.

6	Distance_Unit_Write_Ctrl	Ose
7	output_bit_WriteDistanceUnit	Message Message Control ExplictWriteDistanceUnt

Figure 23: Main Program – Main Routine 6 & 7: Acyclic service (MSG) to write "Distance Unit" of the device.

10.5 Reset acyclic values

In this example the controller tags "Distance_Unit_Read" and "Serial_Number" (see chapter 9 for the controller tag list) can be cleared by the associated controller tag "Reset_Acyclic_Values". See figure 24 for the corresponding routines used to reset the acyclic values.

8	50	MOV- Source 0 Dest Distance_Unit_Read 2 ←
9	Reset_Acyclic_Values	Move Source 0 Dest Serial_Number 70630428 ←

Figure 24: Main Program – Main Routine 8 & 9: Reset some controller tags used for acyclic read services.

11 IP parameter

There are various poss following possibilities IP parameter change

There are various possibilities to change the IP parameter of a selected module / device. See chapter 11.1 and 11.2 for details when using the Logix Designer software or the RSLinx tool.

Remark: In general the IP parameters are changed generically without exception with the acyclic service "Set Attribute Single" via the object 0xF5 / Instance 0x01 / Attribute 5.



11.1 Logix Designer

The IP parameter can be changed according figure 25 in the module properties. There will be a warning to indicate that the access to the device will be lost.

Remark: After the change of the IP parameter, the access to the device will then be lost because of different IP parameter in the PLC project and the device.

Module Properties: Local (50063x and 500702 1.001)			
Internet Protocol (IP) Settings IP settings can be manually configured or can be automatically co if the network supports this capability. (a) Manually configure IP settings	Port Configuration	Network	Ē
IP Settings Configuration Physical Module IP Address: 192 . 168 . 1 . 11	Subnet Mask:	255 . 255 . 255 . 0	
IP Address in physical module does not match address in general properties (192.168.1.10) Copy IP address from general properties. Domgin Name: Hgst Name: Laser Distance Sensor AS2	Gateway Address:	0.0.0.0	
Status: Running	Refresh commun	ication. Set ← Cancel Apply Help	

Figure 25: Module properties (Internet Protocol tab) – Possibility to change IP parameter (Address, subnet mask, etc). Warning: After change of IP address, no more access to the device possible.

11.2 RSLinx

The RSLinx tool is integrated in the Logix Designer software and basically required to connect to the PLC. This tool scans the network and shows all available devices (scanner and adapter). In figure 26 the scanned network with the Laser Distance Sensor and used PLC is shown.

🇞 RSLinx Classic Lite - [RSWho - 1]		-	
Eile View Communications Station DDE/OPC Security Window Help			_ & ×
* 20			
Autobrowse Refresh Browsing - node 192.168	.1.10 found		
Worksteion, LTTHOMAS1 As LTHP3, Ethernet AB_THP3, Ethernet 192168.1.10, Laser Distance Sensor AS2100, Laser Distance Sensor AS2100 B 192168.1.5, 1769-L30ER LOGLX5330ER, 1769-L30ER/A LOGLX5330ER AB_VBP-1, 1789-A17/A Virtual Chassis AB_VEP-2, 1789-A17/A Virtual Chassis	192.168.1.10 Laser Distan	192.168.1.5 1769-L30ER	6
For Help, press F1) ſ	NUM 0	2/19/20 03:12 PM

Figure 26: RSLinx Classic Lite tool (integrated in Logix Designer software) – Network scan: Display all available scanners and adapters.

The IP parameter can be simple changed with this tool. For details how to do this, see figure 27 and 28.

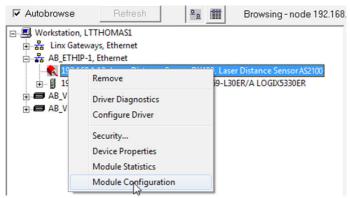


Figure 27: RSLinx Classic Lite tool – Context menu of the desired device \rightarrow Module Configuration: Module configuration window.

General	Port Configuration	Advanced	d Po	rt Cor	figu	ration	N	letwork	
Netwo	rk Configuration Typ	e							
0	Static		Dyn	amic					
0	Use DHCP to obtain	network co	nfig	uratio	n.				
0	Use BOOTP to obtain	n network o	cont	igurat	ion.				
IP Addre	ess:	192	÷	168	•	1	4	11	
Network	Mask:	255		255	•	255	8	0	
Gateway	Address:	0		0		0		0	
Primary I Server:	Name	0		0		0		0	
Seconda Server:	ary Name	0	÷	0	•	0	÷	0	
Domain	Name:								
Host Na	me:	Laser Distance Sensor AS2100							
Status:	Network Inte	rface Confi	gun	ed					

Figure 28: RSLinx Classic Lite tool – Module Configuration (Port Configuration tab): Change of IP parameters e.g. IP address.

After the IP parameter change (new IP: 192.168.1.11) of the selected device (see figure 28) the "old device" (old IP: 192.168.1.10) will be marked as no longer available. See figure 29 for details. At the same time the device with the new IP parameter (192.168.1.11) is now available in the network.



11 IP parameter

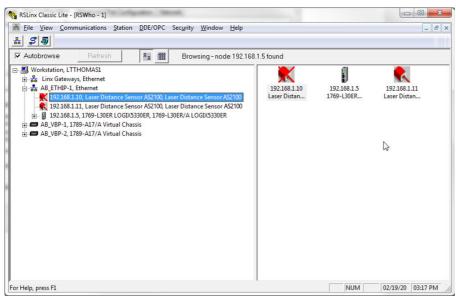


Figure 29: RSLinx Classic Lite tool - Network scan: Display all available and no longer available scanners and adapters.

In addition to the configuration of the IP parameter, the network configuration type can also be configured. Available network configuration types: Static, DHCP and BOOTP.

Remark: For the DHCP and BOOTP types a corresponding BOOTP / DHCP server is required for the assignment of the IP parameter. In figure 30 an example of the simple test tool from Rockwell "BOOTP/DHCP Server" (free-of-charge) is shown.

B	DOTP/DHCP	Server 2.3		43			X
File	Tools He	p					
Re	equest Histo	ry					
	Clear His	tory	Add to Relation List				
	(hr:min:s	Туре	Ethernet Address (M	A IP Address	Hostname		
B	elation List-						
1.00	1	elete	Enable BOOTP E	nable DHCP D	isable BOOTP/DHC	e l	
						·	
+	Ethernet Ac	ldress (N	1A Type IP Addr	ess Hostnar	ne Description		
-St	atus						Entries 0 of 256

Figure 30: BOOTP/DHCP Server tool (Simple test tool from Rockwell) – BOOTP / DHCP server to assign IP addresses to devices on the network. Used for dynamic network configuration types (BOOTP, DHCP).



12 Glossary

AOP	Add On Profile key to unlock additional features (integrated in the EDS file).
BOOTP / DHCP	Different network configuration type: Bootstrap Protocol (BOOTP) and Dynamic Host Configuration Protocol (DHCP).
EDS	Electronic Data Sheet file. Describes the properties of an adapter or scanner device.
EtherNet/IP™	EtherNet/IP™ is one of the most popular Industrial Ethernet interfaces.
MOV	Move instruction to move a constant or the content of one memory location to another. Detailed information can be found in the Rockwell documentation.
MSG	Message instruction to use acyclic read or write services. Detailed information can be found in the Rockwell documentation.
OSR	One Shot Rising instruction to set or clear the output bit depending on the status of the storage bit. Detailed information can be found in the Rockwell documentation.
PLC	Programmable Logic Controller
Process data	Cyclic data communication of the Industrial Ethernet interfaces.
RPI	Requested Packet Interval. Cyclic process data exchange interval requested for a module / adapter.